## Cornell University

Department of Economics
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## Suggested Solutions for Problem Set \#6

1. (Logit Model, NLS, MLE)
(a) Recall the the following normal equation for NLS (For details, see the lecture note 18).

$$
F(\widehat{\theta})^{\prime}(y-f(\widehat{\theta}))=0
$$

Apply the above to our case. Then, we have the following.

$$
\begin{array}{r}
-2 \sum \frac{1}{\left(1+\exp \left(-\alpha-\beta x_{i}\right)\right)^{2}} \exp \left(-\alpha-\beta x_{i}\right)\left(y-\exp \left(-\alpha-\beta x_{i}\right)\right)=0 \\
-2 \sum \frac{1}{\left(1+\exp \left(-\alpha-\beta x_{i}\right)\right)^{2}} x_{i} \exp \left(-\alpha-\beta x_{i}\right)\left(y-\exp \left(-\alpha-\beta x_{i}\right)\right)=0
\end{array}
$$

NL estimator $\widehat{\alpha}_{N L}, \widehat{\beta}_{N L}$ solves the above system equations.
(b) Conditional variance of $d_{i}$ is $\operatorname{Pr}\left(d_{i}=1 \mid x_{i}\right)\left[1-\operatorname{Pr}\left(d_{i}=1 \mid x_{i}\right)\right]$. Note that this comes from the properties of binomial random variables. Therefore, Exact formula for Conditional Variance is;

$$
\begin{aligned}
\operatorname{Var}\left(d_{i}\right. & \left.\mid x_{i}\right)=\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)} \cdot\left(1-\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right) \\
& =\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)} \cdot \frac{\exp \left(-\alpha-\beta x_{i}\right)}{1+\exp \left(-\alpha-\beta x_{i}\right)}
\end{aligned}
$$

(c) The Second-round estimator is better. This takes into account the information about the variance structure of the error terms. This argument is in line with the fact that GLS is better than OLS when heteroskedasticity is present.
(d) First, we have to figure out the likelihood function of individual obaservations.

$$
P\left(d_{i} \mid x_{i}\right)=\left(\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right)^{d_{i}} \cdot\left(\frac{\exp \left(-\alpha-\beta x_{i}\right)}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right)^{1-d_{i}}
$$

Then, loglikelihood function for individual observation is;
$\ln P\left(d_{i} \mid x_{i}\right)=d_{i} \ln \left(\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right)+\left(1-d_{i}\right) \ln \left(\frac{\exp \left(-\alpha-\beta x_{i}\right)}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right)$
The loglikelihood function is;
$l(\alpha, \beta)=\sum d_{i} \ln \left(\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right)+\sum\left(1-d_{i}\right) \ln \left(\frac{\exp \left(-\alpha-\beta x_{i}\right)}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right)$
We can obtain the ML estimator from the first order conditions of the loglikelihood function.

$$
\begin{aligned}
\frac{\partial l(\alpha, \beta)}{\partial \alpha}= & \sum d_{i}\left(1-\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right)-\sum\left(1-d_{i}\right)\left(\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right) \\
= & 0 \\
\frac{\partial l(\alpha, \beta)}{\partial \beta}= & \sum d_{i}\left(1-\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right) x_{i} \\
& -\sum\left(1-d_{i}\right)\left(\frac{1}{1+\exp \left(-\alpha-\beta x_{i}\right)}\right) x_{i} \\
= & 0
\end{aligned}
$$

ML estimators, $\widehat{\alpha}_{M L}, \widehat{\beta}_{M L}$ solves the above.
Tips for obtaining FOC in the logit model:
Suppose that $F_{i}\left(x_{i} \beta\right)=\frac{1}{1+\exp \left(-x_{i} \beta\right)}\left(x_{i}\right.$ can be a vector in this tip).
Then, $\exp \left(-x_{i} \beta\right)=\frac{1}{F_{i}}-1$.
Also, $F_{i}^{\prime}=\left(\frac{1}{1+\exp \left(-x_{i} \beta\right)}\right)^{2} \exp \left(-x_{i} \beta\right) \cdot x_{i}=F_{i}^{2}\left(\frac{1}{F_{i}}-1\right) x_{i}=F_{i}(1-$ $\left.F_{i}\right) x_{i}$
Using the above tip, we can easily get the FOC.
(Using the similar method, the hessian can be obtained by the formula that $\left.H=-\sum F_{i}\left(1-F_{i}\right) x_{i} x_{i}^{\prime}\right)$
2. (Measurement error problem, NLS, IV, GMM)
(a) Note that $t_{i}$ is not observable, so we have to use $t^{*}$ as a proxy. Then, we can run Nonlinear Least Squares (NLS).
However, there may be a "endogeneity" problem, that is, $t^{*}$ and error term might be correlated. If endogeneity is present, we cannot obtain consistent estimator from Nonlinear Least Squares.
To avoid this problem, we're going to use instrumental variable technique (IV). Solve $z^{\prime}(d-E d)=0$, where $z$ is $N \times K$ instrumental
variable vector, $d-E d$ is $N \times 1$ vector (you may understand how it is deifned). If this is overidentified case, we cannot have a solution. So let's apply "GLS" idea, that is, solve the following.

$$
\operatorname{Arg} \min (d-E d)^{\prime} z \operatorname{Var}\left(z^{\prime}(d-E d)\right)^{-1} z^{\prime}(d-E d)
$$

But, what is $\operatorname{Var}\left(z^{\prime}(d-E d)\right)^{-1}$ ? $\operatorname{Var}\left(z^{\prime}(d-E d)\right.$ have the following form.
$\operatorname{Var}\left(z^{\prime}(d-E d)\right)=z^{\prime}\left(\begin{array}{cccc}F_{1}\left(1-F_{1}\right) & 0 & \cdots & 0 \\ 0 & F_{2}\left(1-F_{2}\right) & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & F_{N}\left(1-F_{N}\right)\end{array}\right) z$,
where $F_{i}=F\left(x_{i}^{\prime} \beta+\delta \widehat{t_{i}^{*}}\right)$. Hence, in order to evaluate the above consistently, we need consistent estimator for $\beta$ and $\delta$. I suggest 2 stage method, which is analogous to feasible 3SLS. In the first stage, solve the following:

$$
\underset{\beta, \delta}{\operatorname{Arg} \min }(d-E d)^{\prime} z z^{\prime}(d-E d)
$$

where the weighting matrix is just an identity matrix. Although it may not be efficient, we can obtain a consistent estimator. Let us call it $(\widetilde{\beta}, \widetilde{t})$. Then evaluate $\operatorname{Var}\left(z^{\prime}(d-E d)\right.$ at this consistent estimator. Let us call it $\widetilde{\Omega}$. As a second stage, solve the following:

$$
\underset{\beta, \delta}{\operatorname{Arg} \min }(d-E d)^{\prime} z \widetilde{\Omega}^{-1} z^{\prime}(d-E d)=0
$$

The resulting estimator is more efficient than that from the first stage.
(b) Note that $\widehat{\delta}_{I V}$ is consistent in any case, so long as $z$ is exogenous. However, $\widehat{\delta}_{N L S}$ is consistent only when endogeneity is not present. Therefore, we can test measurement error problem by comparing $\widehat{\delta}_{I V}$ and $\widehat{\delta}_{N L S}$. If they are too different, we can say that there is a serious measurement error problem (endogeneity problem).
3. (Logit, MLE)
(a) Since we have $\mathrm{N} / 3$ iid Bernoulli observations, say $y_{1}, \ldots, y_{N / 3}$, MLE $\widehat{F}_{1}=\sum_{\left\{x_{i}=1\right\}} y_{i} /(N / 3)$. Therefore, we have

$$
\begin{aligned}
E\left(\widehat{F}_{1}\right) & =\frac{\sum_{\left\{x_{i}=1\right\}} E\left(y_{i}\right)}{N / 3}=\frac{\sum_{\left\{x_{i}=1\right\}} F_{1}}{N / 3}=F_{1}, \\
\operatorname{Var}\left(\widehat{F}_{1}\right) & =\frac{\sum_{\left\{x_{i}=1\right\}} \operatorname{Var}\left(y_{i}\right)}{(N / 3)^{2}}=\frac{F_{1}\left(1-F_{1}\right)}{N / 3} .
\end{aligned}
$$

(b) Log likelihood function is as follows:
$l(\beta)=\sum\left[y_{i} \ln \left(\frac{1}{1+\exp \left(-x_{i} \beta\right)}\right)+\left(1-y_{i}\right) \ln \left(\frac{\exp \left(-x_{i} \beta\right)}{1+\exp \left(-x_{i} \beta\right)}\right)\right]$.
MLE is the maximizer of this likelihood function. For the asymptotic variance, we calculate (expected) hessian matrix, $H$. If we define $\Lambda_{i}=\left\{1 /\left(1+\exp \left(-x_{i} \beta\right)\right)\right\}$, we have $H=-\sum \Lambda_{i}\left(1-\Lambda_{i}\right) x_{i} x_{i}^{\prime}$. Therefore, we have

$$
\begin{aligned}
& \sqrt{N}(\widehat{\beta}-\beta) \xrightarrow{d} N\left(0,\left[p \lim \frac{1}{N} \sum \Lambda_{i}\left(1-\Lambda_{i}\right) x_{i} x_{i}^{\prime}\right]^{-1}\right) \\
= & N\left(0,\left[\frac{1}{3} F_{1}\left(1-F_{1}\right)+\frac{4}{3} F_{2}\left(1-F_{2}\right)\right]^{-1}\right) .
\end{aligned}
$$

(c) Since $\widehat{F}_{1}=1 /(1+\exp (-\widehat{\beta}))$, from the delta method and the fact that $F_{1}^{\prime}(\beta)=F_{1}\left(1-F_{1}\right)$, we have

$$
\sqrt{N}\left(\widehat{F}_{1}-F_{1}\right) \xrightarrow{d} N\left(0, F_{1}^{2}\left(1-F_{1}\right)^{2}\left[\frac{1}{3} F_{1}\left(1-F_{1}\right)+\frac{4}{3} F_{2}\left(1-F_{2}\right)\right]^{-1}\right) .
$$

(d) The asymptotic variance of $\widehat{F}_{1}$ in (c) is smaller than or equal to the variance from (a). But (c) requires more computation and the logistic assumption should be the correct specification.
(e) If the logit specification is correct, estimators should converge to the true values $F_{1}, F_{2}$ and $F_{3}$. Therefore we can compute them with the estimator from (a) which are certainly consistent estimators.
4. (MLE)
(a) Note that $c_{i} \exp \left(-y_{i}\left(x_{i} \beta\right)\right)$ is a conditional density function (likelihood function) given $x_{i}$ and $\beta$ and that $y_{i}$ follows exponential distribution. So, we must have the following.

$$
\int_{0}^{\infty} c_{i} \exp \left(-y\left(x_{i} \beta\right)\right) d y=1
$$

Then, we have $c_{i}=x_{i} \beta$.
For a sample of N independent observations $\left(y_{i}, x_{i}\right)$,
(b) First, construct loglikelihood function.

$$
\begin{aligned}
p_{i}\left(y_{i}\right. & \left.\mid x_{i}, \beta\right)=x_{i} \beta \exp \left(-y_{i}\left(x_{i} \beta\right)\right) \\
\ln p_{i} & =\ln \left(x_{i} \beta\right)-y_{i}\left(x_{i} \beta\right) \\
l(\beta) & =\sum \ln p_{i}=\sum \ln \left(x_{i} \beta\right)-\sum y_{i}\left(x_{i} \beta\right)
\end{aligned}
$$

Second, let's calculate a score function. This is the First Order Condition of the above loglikelihood function.

$$
S=\frac{\partial l(\beta)}{\partial \beta}=\sum \frac{x_{i}^{\prime}}{x_{i} \beta}-\sum y_{i} x_{i}^{\prime}(\text { This is } k \times 1 \text { vector })
$$

Let's compute a hessian function.

$$
H=\frac{\partial^{2} l(\beta)}{\partial \beta \partial \beta^{\prime}}=-\sum \frac{x_{i}^{\prime} x_{i}}{\left(x_{i} \beta\right)^{2}}(\text { This is } k \times k \text { vector })
$$

(c) We know that $\sqrt{N}\left(\beta_{M L}-\beta\right) \stackrel{\text { Asy. }}{\sim} N\left(0, i_{0}^{-1}\right)$.

And $i_{0}=-p \lim \left(\frac{H}{N}\right)$.
Therefore, the asymptotic distribution is as follows.

$$
\sqrt{N}\left(\beta_{M L}-\beta\right) \stackrel{A s y .}{\sim} N\left(0, p \lim \left(\frac{\sum \frac{x_{i}^{\prime} x_{i}}{\left(x_{i} \beta\right)^{2}}}{N}\right)^{-1}\right)
$$

Now you want to plot some "residuals" to check the specification. Hence, you need a transformation $z_{i}$ of $y_{i}$, given $x_{i}$ and $\beta$, such that the distribution of z does not depend on x and $\beta$. Consider the random variable $z_{i}=1-\exp \left(-y_{i}\left(x_{i} \beta\right)\right)$.
(d) Note that $1-\exp \left(-y_{i}\left(x_{i} \beta\right)\right)$ is a CDF of exponential distribution, so $z_{i}$ can take values from 0 to 1 . Let's call it F , that is, $z_{i}=F\left(y_{i}\right)$ given $x_{i}, \beta$.
Then, $P\left(z_{i} \leq \widetilde{z}\right)=P\left(F\left(y_{i}\right) \leq \widetilde{z}\right)=P\left(F^{-1}\left(F\left(y_{i}\right)\right) \leq F^{-1}(\widetilde{z})\right)$ since F is strictly increasing in $(0,1)$.
Now, we have $P\left(F^{-1}\left(F\left(y_{i}\right)\right) \leq F^{-1}(\widetilde{z})\right)=P\left(y_{i} \leq F^{-1}(\widetilde{z})\right)$. And we know that $y_{i}$ follows exponential distribution, so $P\left(y_{i} \leq F^{-1}(\widetilde{z})\right)=$ $\left.F\left(F^{-1}(\widetilde{z})\right)\right)=\widetilde{z}$.
The last formula implies that $P\left(z_{i} \leq \widetilde{z}\right)=\widetilde{z}$ and that $z_{i}$ follows a uniform distribution whose support is $(0,1)$.
Suppose you calculate z using $\beta_{M L}$ instead of $\beta$ and you plot the empirical cdf F-hat $(\mathrm{t})=\left(\# z_{i} \leq t\right) / N$.
(e) If the model is correct and the estimate is good, our empirical cdf should look like real cdf (cdf of uniform distribution). Therefore, the plot should look like 45 degree line in $(0,1)$.
5. (K-variable Regression)
(a) We have

$$
b^{*}=\frac{\sum x_{i} y_{i}}{\sum x_{i}^{2}}=\frac{\sum x_{i}^{4}}{\sum x_{i}^{2}}
$$

So, conditional expectation and conditional variance of $b^{*}$ are

$$
\begin{aligned}
E_{x}\left(b^{*}\right) & =\frac{\sum x_{i}^{4}}{\sum x_{i}^{2}}, \\
\operatorname{Var}_{x}\left(b^{*}\right) & =0 .
\end{aligned}
$$

(b) Note that, when x follows standard normal, we have

$$
\begin{aligned}
E\left(x^{n}\right) & =(n-1)(n-3) \ldots 1 \quad \text { when } n \text { is odd } \\
& =0 \quad \text { when } n \text { is even. }
\end{aligned}
$$

Therefore, we have

$$
b=\frac{E x y}{E x^{2}}=\frac{E x^{4}}{E x^{2}}=\frac{3}{1}=3
$$

(c) Note that

$$
\begin{aligned}
t= & \frac{\widehat{b}}{S / \sqrt{\sum x_{i}^{2}}} \text { and } p \lim \widehat{b}=3 \\
& \text { and standard error is } S / \sqrt{\sum x_{i}^{2}}
\end{aligned}
$$

$S^{2}$ can be represented as

$$
\begin{aligned}
S^{2} & =\frac{\sum\left(y_{i}-\widehat{b} x_{i}\right)^{2}}{N-1}=\frac{\sum y_{i}^{2}-2 \widehat{b} \sum x_{i} y_{i}+\widehat{b}^{2} \sum x_{i}^{2}}{N-1} \\
& =\frac{N}{N-1} \frac{\sum x_{i}^{6}-2 \widehat{b} \sum x_{i}^{4}+\widehat{b}^{2} \sum x_{i}^{2}}{N} .
\end{aligned}
$$

Therefore,

$$
p \lim S^{2}=p \lim \frac{N}{N-1} \cdot p \lim \frac{\sum x_{i}^{6}-2 \widehat{b} \sum x_{i}^{4}+\widehat{b}^{2} \sum x_{i}^{2}}{N}=6
$$

So we have $p \lim S=\sqrt{6}$ (Apply the law of large numbers above). Furthermore,

$$
\begin{aligned}
t & =\frac{3}{\sqrt{6}} \sqrt{\sum x_{i}^{2}}=\sqrt{N} \cdot \frac{3}{\sqrt{6}} \cdot \sqrt{\frac{\sum x_{i}^{2}}{N}} \\
& \approx \frac{3}{\sqrt{6}} \sqrt{N}
\end{aligned}
$$

and standard error is approximately $\sqrt{6 / N}$. Next, $R^{2}$ can be approximated as follows:

$$
R^{2}=\frac{\widehat{b}^{2} \sum x_{i}^{2}}{\sum y_{i}^{2}}=\frac{\widehat{b}^{2} \sum x_{i}^{2} / N}{\sum y_{i}^{2} / N} \xrightarrow{p} \frac{9}{15}=\frac{3}{5} .
$$

(d) Now we estimate the model, $y_{i}=b_{1} x_{i}+b_{2} x_{i}^{2}+\varepsilon_{i}$. Note that $x_{i}$ and $x_{i}^{2}$ are orthogonal since $E\left(x_{i}^{3}\right)=0$. Hence, we have

$$
\widehat{b}_{2}=\frac{\sum x_{i}^{2} y_{i}}{\sum x_{i}^{4}}=\frac{\sum x_{i}^{5} / \sqrt{N}}{\sum x_{i}^{4} / \sqrt{N}} \xrightarrow{p} 0 .
$$

For a plot of actual vs. fitted values, draw $y=x^{3}$ and $y=3 x$ on the same $x y$ graph.
6. (Gauss-Markov Thorem)
(a) The OLS esimator, $\widehat{\beta}_{O L S}$ is $\left(X^{\prime} X\right)^{-1} X^{\prime} y$. Clearly, it is a linear estimator, where $c^{\prime}=\left(X^{\prime} X\right)^{-1} X^{\prime}$.
(b) There can be a lot of examples for this. Suppose that $c^{\prime}=2\left(X^{\prime} X\right)^{-1} X^{\prime}$. Then, $T(y)=2\left(X^{\prime} X\right)^{-1} X^{\prime} y$. It is easy to show that $E[T(y)]=2 \beta \neq$ $\beta$ unless $\beta=0$.
(c) MSE of the OLS estimator

$$
\begin{aligned}
m(T(y), \beta)_{O L S} & =E\left[(T(y)-\beta)(T(y)-\beta)^{\prime}\right] \\
& \left.\left.=E\left[\left(X^{\prime} X\right)^{-1} X^{\prime} y-\beta\right)\left(X^{\prime} X\right)^{-1} X^{\prime} y-\beta\right)^{\prime}\right] \\
& =E\left[\left(X^{\prime} X\right)^{-1} X^{\prime} \epsilon \epsilon^{\prime} X\left(X^{\prime} X\right)^{-1}\right] \\
& =\left(X^{\prime} X\right)^{-1} X^{\prime} E\left[\epsilon \epsilon^{\prime}\right] X\left(X^{\prime} X\right)^{-1} \\
& =\sigma^{2}\left(X^{\prime} X\right)^{-1}
\end{aligned}
$$

(d) MSE of an arbitrary linear estimator

$$
\begin{aligned}
m(T(y), \beta)= & E\left[(T(y)-\beta)(T(y)-\beta)^{\prime}\right] \\
= & E\left[\left(c^{\prime} y-\beta\right)\left(c^{\prime} y-\beta\right)^{\prime}\right] \\
= & E\left[c^{\prime} y y^{\prime} c-\beta y^{\prime} c-c^{\prime} y \beta^{\prime}+\beta \beta^{\prime}\right] \\
= & E\left[c^{\prime}(X \beta+\epsilon)(X \beta+\epsilon)^{\prime} c-\beta(X \beta+\epsilon)^{\prime} c-c^{\prime}(X \beta+\epsilon) \beta^{\prime}+\beta \beta^{\prime}\right] \\
= & E\left[c^{\prime} X \beta \beta^{\prime} X^{\prime} c+c^{\prime} X \beta \epsilon^{\prime} c+c^{\prime} \epsilon \beta^{\prime} X^{\prime} c+c^{\prime} \epsilon \epsilon^{\prime} c-\beta \beta^{\prime} X^{\prime} c-\beta \epsilon^{\prime} c\right. \\
& \left.-c^{\prime} X \beta \beta^{\prime}-c^{\prime} \epsilon \beta^{\prime}+\beta \beta^{\prime}\right] \\
= & c^{\prime} X \beta \beta^{\prime} X^{\prime} c+c^{\prime} X \beta E\left(\epsilon^{\prime}\right) c+c^{\prime} E(\epsilon) \beta^{\prime} X^{\prime} c+c^{\prime} E\left(\epsilon \epsilon^{\prime}\right) c-\beta \beta^{\prime} X^{\prime} c \\
& -\beta E\left(\epsilon^{\prime}\right) c-c^{\prime} X \beta \beta^{\prime}-c^{\prime} E(\epsilon) \beta^{\prime}+\beta \beta^{\prime} \\
= & c^{\prime} X \beta \beta^{\prime} X^{\prime} c+\sigma^{2} c^{\prime} c-\beta \beta^{\prime} X^{\prime} c-c^{\prime} X \beta \beta^{\prime}+\beta \beta^{\prime}
\end{aligned}
$$

(e) Yes, this is true. In order for boundedness to be guaranteed, unbiasedness should be satisfied. Then, we can apply the Gauss Markov Theorem.
(f) Consider the MSE of an arbitrary linear estimator, $m(T(y), \beta)=$ $c^{\prime} X \beta \beta^{\prime} X^{\prime} c+\sigma^{2} c^{\prime} c-\beta \beta^{\prime} X^{\prime} c-c^{\prime} X \beta \beta^{\prime}+\beta \beta^{\prime}$. This is a quadratic
function of $\beta$. This function can take positive or negative infinity since $\beta \in R^{k}$.
Therefore, to obtain bounded MSE, there should be no term including $\beta$ in the above formula. The only way of excluding $\beta$ is to have that $c^{\prime} X=I$. Then, only $\sigma^{2} c^{\prime} c$ will be left. This is nothing but a unbiasedness condition of linear estimator. Hence, we can apply the Gauss Markov Theorem; The OLS estimator has minimum variance.
7. (NLS, IV, GMM)
(a) Noting that the homogeneous ODE, $y^{\prime}-\beta y=0$ has the solution $y_{h}=C e^{b x}$, we can find a particular solution $y_{p}=\gamma+\alpha x$. Hence the solution is $y=\gamma+\alpha x+C e^{b x}$. From the initial condition we have $C=1$. The model would be $y_{i}=\gamma+\alpha x_{i}+e^{\beta x_{i}}+\varepsilon_{i}$ with $\varepsilon_{i} \sim i i d\left(0, \sigma^{2}\right)$.
(b) The normal equation for a nonlinear model $y=F(x ; \gamma, \alpha, \beta)$ is $F^{\prime}(\gamma, \alpha, \beta)(y-F(\gamma, \alpha, \beta))=0$. Since $F^{\prime}=\left(1, x, x e^{\beta x}\right)^{T}$, the normal equation is

$$
\begin{aligned}
\sum\left[y_{i}-\left(\gamma+\alpha x_{i}+e^{\beta x_{i}}\right)\right] & =0, \\
\sum x_{i}\left[y_{i}-\left(\gamma+\alpha x_{i}+e^{\beta x_{i}}\right)\right] & =0, \\
\sum x_{i} e^{\beta x_{i}}\left[y_{i}-\left(\gamma+\alpha x_{i}+e^{\beta x_{i}}\right)\right] & =0 .
\end{aligned}
$$

(c) Given a value of $\beta$, it becomes a standard LS problem. We can solve for $\gamma$ and $\alpha$ in terms of $\beta$ then the problem is one dimensioanl optimization with respect to $\beta$ only.
(d) "normal equation" become $z^{\prime}(y-E y)=0$. In terms of GMM, you have k moment conditions. In this overidentified case, these equation cannot be solved directly and GLS must be used on them. Thus minimize $(y-E y)^{\prime} z\left(z^{\prime} z\right)^{-1} z^{\prime}(y-E y)$ with FOC (normal equations) $F^{\prime} z\left(z^{\prime} z\right)^{-1} z^{\prime}(y-E y)=0$.
(e) We can compute the estimator from (b) and (d). If x is endogenous, they should be different significantly.

